

Partial Transportability for Domain Generalization

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Introduction

- We develop a framework to provide performance guarantees for predictions made in an unseen domain using knowledge of causal relations encoded in selection diagrams.
- It is based on Neural Causal Models (NCMs) and is the first general estimation technique for transportability problems [1, 2].

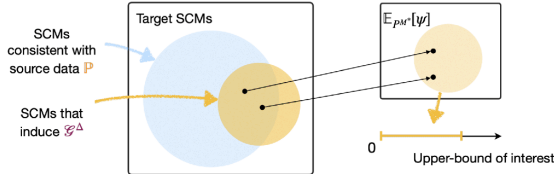


Figure 1. Partial Transportability Task.

Task: Find the tightest bound:

$$\mathbb{E}_{P^{M^*}}[\psi(\mathbf{V})] \leq q_{\max}, \quad (1)$$

$\forall \mathcal{M} : \{M^1, \dots, M^k, M^*\}$ that induce \mathcal{G}^Δ and $\mathbb{P} : \{P^1, \dots, P^k\}$.

Example

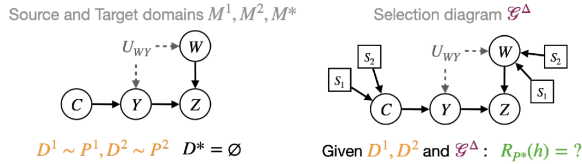


Figure 2. Selection diagrams encode structural invariances.

- **Input:** A classifier h , assumptions encoded in selection diagrams \mathcal{G}^Δ , and data samples from source domains $D^1, D^2 \sim P^1, P^2$.
- **Goal:** Evaluate the worst case error in target M^* ,

$$\max_{\text{target distributions } P^*} R_{P^*}(h), \quad R_P(h) := \mathbb{E}_P[\mathcal{L}(y, h(\mathbf{x}))] \quad (2)$$

of three baseline classifiers:

$$h_1(\mathbf{c}, w) := w \oplus_{c \in \mathbf{c}} c, \quad h_2(\mathbf{c}) := \bigoplus_{c \in \mathbf{c}} c, \quad h_3(z) := z$$

Classifier	$R_{P^{M^1}}$	$R_{P^{M^2}}$	$R_{P^{M^*}}$
$h_1(\mathbf{c}, w)$	1%	4%	49%
$h_2(\mathbf{c})$	20%	20%	20%
$h_3(z)$	3%	5%	4%

Table 1. In-domain and worst-case out-of-domain error of classifiers.

Research Questions

Q1: Evaluate the worst-case error of a classifier h in M^* ,

$$\max_{M^* \in \text{tuple of SCMs } \mathcal{M} \text{ that entails } \mathbb{P} \text{ \& induces } \mathcal{G}^\Delta} R_{P^{M^*}}(h). \quad (3)$$

Q2: Optimize h for best worst-case performance in M^* ,

$$\arg \min_h \max_{M^* \in \text{tuple of SCMs } \mathcal{M} \text{ that entails } \mathbb{P} \text{ \& induces } \mathcal{G}^\Delta} R_{P^{M^*}}(h). \quad (4)$$

Q1: Evaluation by fitting NCMs

Theorem (Neural-TR). Given \mathcal{G}^Δ and distributions \mathbb{P} ,

$$\max_{M^* \in \text{tuple of NCMs } \mathcal{M} \text{ that entails } \mathbb{P} \text{ \& induces } \mathcal{G}^\Delta} R_{P^{M^*}}(h) \quad (5)$$

is a tight upper-bound on the target risk.

- NCMs are SCMs parameterized by NN.
- NCMs can be used to encode all constraints in Transportability tasks.
- Sound only in discretely-valued systems

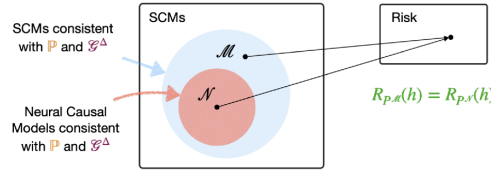


Figure 3. Expressiveness of NCMs for Transportability task.

Q2: Optimization by Adversarial Training

The CRO algorithm starts with a random classifier h_t and an empty set \mathbb{D} . It proceeds until the error converges, as follows:

1. Run evaluation (Neural-TR) on h_t and obtain M_t that entails the worst-case error.
2. Generate adversarial data $D_t \sim P_{M_t}, \mathbb{D} = \mathbb{D} \cup D_t$.
3. Train new classifier h_{t+1} to minimize $\max_{D \in \mathbb{D}} R_D(h)$, and iterate ...

Theorem (CRO). Given \mathcal{G}^Δ and distributions \mathbb{P} ,

$$\text{CRO} \in \arg \min_h \max_{M^* \in \text{tuple of SCMs } \mathcal{M} \text{ that entails } \mathbb{P} \text{ \& induces } \mathcal{G}^\Delta} R_{P^{M^*}}(h). \quad (6)$$

- In fact, with CRO we show that h_3 is **optimal** in the worst-case.

Simulations

- We consider the colored MNIST (CMNIST) dataset.
- The task is to use 2 source dataset to optimize for the worst-case performance in a test domain in which the color assignment may be arbitrary.
- After three iterations CRO converges to a classifier with an error of 25% in the worst-case, which is theoretically optimal.

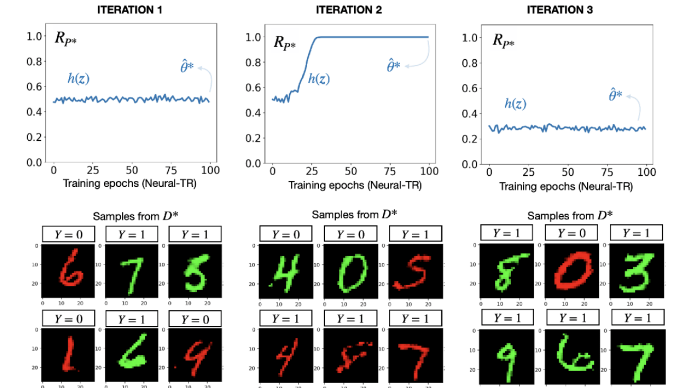


Figure 4. CMNIST.

Acknowledgements

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References

- [1] Elias Bareinboim and Judea Pearl. Causal inference and the data-fusion problem. PNAS, 2016.
- [2] Kevin Xia, Kai-Zhan Lee, Yoshua Bengio, and Elias Bareinboim. The causal-neural connection: Expressiveness, learnability, and inference. NeurIPS, 2021.



Figure 5. Paper link.